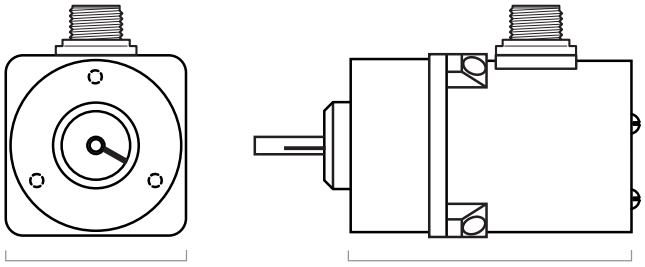
RT8DN

0–45° to 0–200 Turns • DeviceNET®

Industrial Grade Rotational Position Sensor
Absolute Rotary Position up to 200 turns
Aluminum or Stainless Steel Enclosure Options
IP68 / NEMA 6





2.5" [64 mm] 4.0" [102 mm]

GENERAL

Full Stroke Range Options	0-0.125 to 0-200 turns
Electrical Interface	CANbus ISO 11898
Protocol	DeviceNet Version 2.0
Accuracy	see ordering information
Repeatability	± 0.02% full stroke
Resolution	± 0.003% full stroke
Enclosure Material Options	powder-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Shaft Loading	up to 10 lbs. radial and 5 lbs. axial
Starting Torque (25°C)	2.0 in-oz., max.
Weight, Aluminum (Stainless Steel) Enclosure	3 lbs. (6 lbs.) max.

ELECTRICAL

Input Voltage	Bus Powered
Input Current	40 mA max.
Address Setting (Node ID)	0...63 set via DIP Switches (default setting: 63)
Baud Rate	125K, 250K or 500K set via DIP Switches
EDS file	available @ http:/celesco.com/downloads

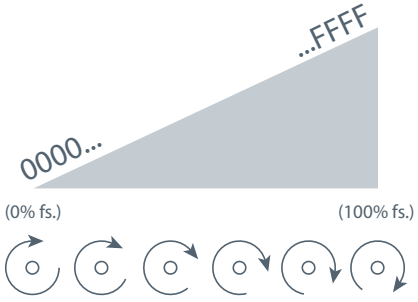
ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67/68
Operating Temperature	-40° to 200°F (-40° to 90°C)
Vibration	up to 10 g to 2000 Hz maximum

Our model RT8DN communicates rotational position feedback via DeviceNET® to your programmable controller. The heart of this sensor is a precision plastic-hybrid position potentiometer which provides a "absolute" position and does not ever have to be reset to a "home" position after a power loss or planned shutdown.

This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/8 to 200 turns.

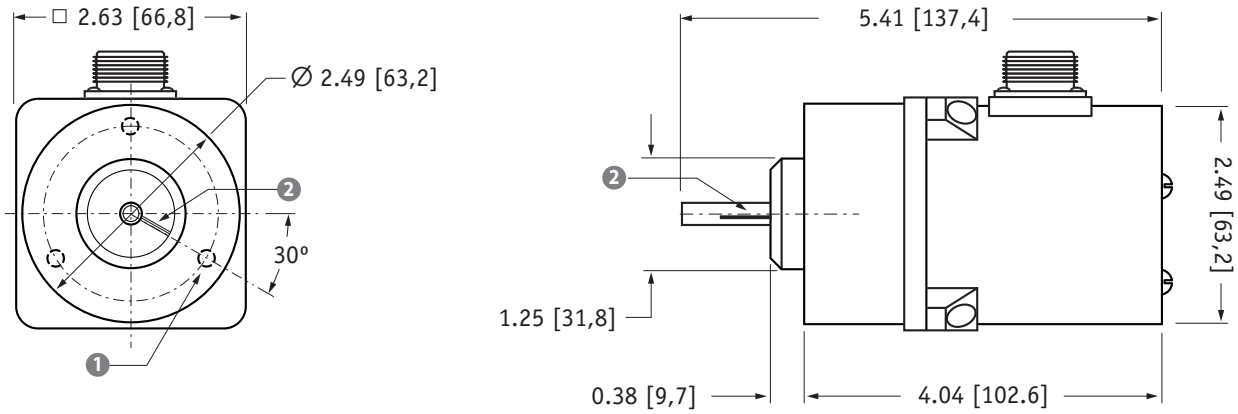
Output Signal:



20630 Plummer Street • Chatsworth, CA 91311
tel: 800.423.5483 • +1.818.701.2750 • fax: +1.818.701.2799

celesco

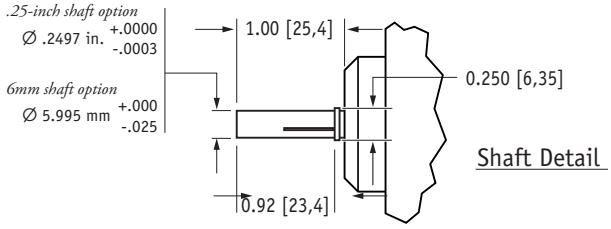
Outline Drawing:



1 *mounting holes:*
for .25 in. shaft option, mounting holes are threaded #10-32 x 0.375 deep 120° apart on a 2.00 inch dia. BC

for 6mm shaft option, mounting holes are threaded M6 x 9 mm deep 120° apart on a 50,8 mm dia. BC

2 *reference mark:*
full counter-clockwise position - align mark on shaft to mark on face for start of measurement range



Shaft Detail

DIMENSIONS ARE IN INCHES [MM]
tolerances are ±0.02 in. [±0,5 mm] unless otherwise noted

Ordering Information:

Model Number:

RT8DN - _____ - ___ - ___ - ___ - ___ - ___ - ___ - ___
order code: ⓡ ⓐ ⓑ ⓒ ⓓ ⓔ ⓕ

Sample Model Number:

RT8DN - 100 - AL - 25 - FL - 500 - TR - SC5

ⓡ	range:	100 turns
ⓐ	enclosure:	powder-painted aluminum
ⓑ	shaft:	.25-in diameter
ⓒ	mounting style:	flange
ⓓ	baud rate:	500 k bits/sec.
ⓔ	terminating resistor:	yes
ⓕ	electrical termination:	5-meter cordset with straight plug

Full Stroke Range:

ⓡ *order code:*	R125	R25	R50	1	2	3	5	10	20
clockwise shaft rotations, min:	0.125	0.25	0.50	1	2	3	5	10	20
accuracy (% of f.s.):	1.25%	1.25%	0.5%	0.5%	0.5%	0.2%	0.2%	0.15%	0.15%
potentiometer cycle life*:	2.5×10^6	2.5×10^6	2.5×10^6	2.5×10^6	2.5×10^6	5×10^5	5×10^5	2.5×10^5	2.5×10^5

ⓡ *order code:*	30	40	50	80	100	120	140	180	200
clockwise shaft rotations, min:	30	40	50	80	100	120	140	180	200
accuracy (% of f.s.):	0.15%	0.15%	0.15%	0.15%	0.15%	0.15%	0.15%	0.15%	0.15%
potentiometer cycle life*:	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5	2.5×10^5

**–number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.*

Enclosure Material:

ⓐ *order code:*	AL	SS
	powder-painted aluminum	303 stainless steel

Shaft Diameter:

ⓑ *order code:*	25	6	25F	6F
	0.25-in. diameter	6 mm diameter	0.25-in. dia. w/flats	6 mm dia. w/flats

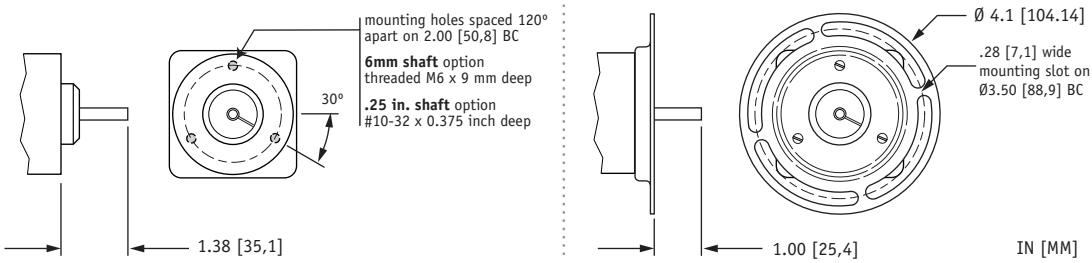


Ordering Information (cont.):

Mounting Style:

C *order code:*

FA	FM
face mount	flange mount



Baud Rate:

D *order code:*

125	250	500
125 kbaud	250 kbaud	500 kbaud

Terminating Resistor:

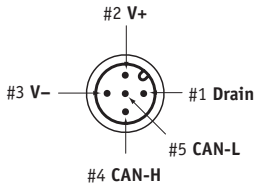
E *order code:*

TR	NR
terminating resistor	no terminating resistor

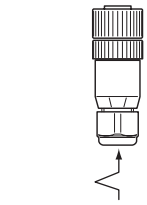
Electrical Connection:

F *order code:*

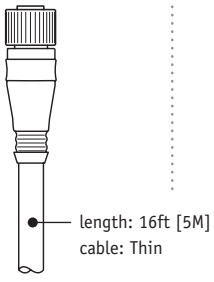
blank	MC5	SC5	NC5
5-pin micro-connector *(no mating plug supplied)*	5-pin micro-connector w/ mating plug	5-pin micro-connector and 5 meter length cordset w/straight mating plug	5-pin micro-connector and 5 meter length cordset w/90° mating plug



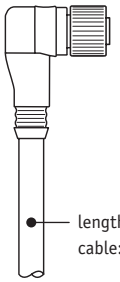
connector (contact view)



0.16" - 0.32" OD Cable (THIN)

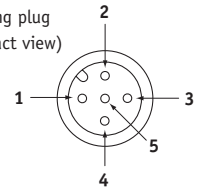


length: 16ft [5M]
cable: Thin



length: 16ft [5M]
cable: Thin

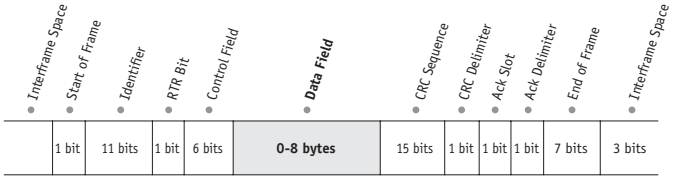
mating plug (contact view)



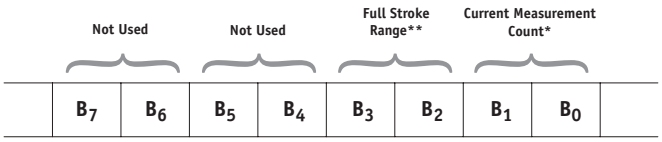
pin	signal	wire color
1	drain	brown
2	V+	white
3	V-	blue
4	Can-H	black
5	Can-L	grey

I/O Format:

Data Frame



Data Field



B_0 = LSB current measurement byte
B_1 = MSB current measurement byte
B_2 = LSB full stroke range byte
B_3 = MSB full stroke range byte
B_4 - B_7 = not used

***Current Measurement Count**

The **C**urrent **M**easurement **C**ount (**CMC**) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies the first two bytes (B_0 and B_1) of the data field. B_0 is the LSB (least significant byte) and B_1 is the MSB (most significant byte).

The CMC starts at 0000H with shaft at the full counter-clockwise position (0° reference mark) and continues in the clockwise direction to the end of the stroke range stopping at FFFFH. This holds true for all ranges.

****Full Stroke Range**

The **F**ull **S**troke **R**ange **(FSR)** is a 16-bit value in the data field that expresses the full range of the sensor in degrees. This value can be used to convert the actual count to units of measurement should the application require it.

The full stroke measurement range occupies the second two bytes (B_2 and B_3) of the data field.

B_2 is the LSB (least significant byte) and B_3 is the MSB (most significant byte).

This value is expressed in degrees.

Example:

Hex Value	*Decimal Equivalent*	*Full Stroke Range*
0168	360	360 degrees

Converting CMC to Degrees

If required, the CMC can easily be converted to a rotational measurement expressed in degrees instead of counts.

This is accomplished by first dividing the CMC by 65,535 (total counts over the range) and then multiplying that value by the FSR:

$$\left(\frac{\text{CMC}}{65{,}535}\right) \text{X FSR}$$

Example:

If the full stroke range is **1 turn (360 degrees)** and the current position is **OFF2 Hex** (4082 Decimal) then,

$$\left(\frac{4082}{65{,}535}\right) \text{X } 360 \text{ deg.} = 22.4 \text{ degrees}$$

Address Setting (Node ID), Baud Rate and Bus Termination Settings

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number **1** (= 2^0) and ending with switch number **6** (= 2^5).

DIP-1 (2^0)	DIP-2 (2^1)	DIP-3 (2^2)	DIP-4 (2^3)	DIP-5 (2^4)	DIP-6 (2^5)	*address* (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
…	…	…	…	…	…	…
1	1	1	1	1	1	63



Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches **7** & **8** on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

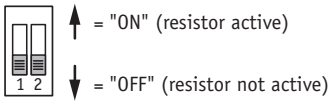
DIP-7	DIP-8	baud rate
0	0	125k
1	0	250k
0	1	500k
1	1	125k



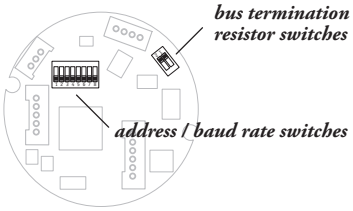
Bus Termination

The setting of the internal bus termination resistor may be specified upon order or manually changed by the end user at the time of installation.

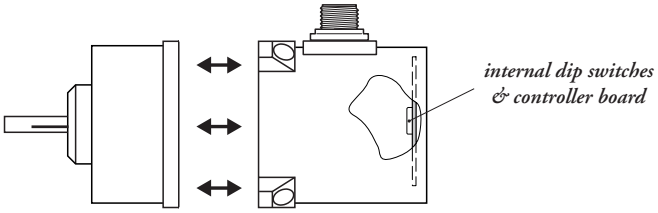
The bus termination resistor is activated setting switches **1** & **2** on the 2-pole DIP switch (located on the internal DeviceNET controller board) to the "ON" position.



DeviceNET Controller Board and DIP Switch Location



to gain access to the controller board, remove four Allen-Head Screws and separate case halves



version: **6.0** last updated: **February 28, 2014**